

APPLICATION NOTE

BACKGROUND INFORMATION.

There are lots of inquiries about the phase angle regulation systems, especially regarding to the control signals and to the output voltage.

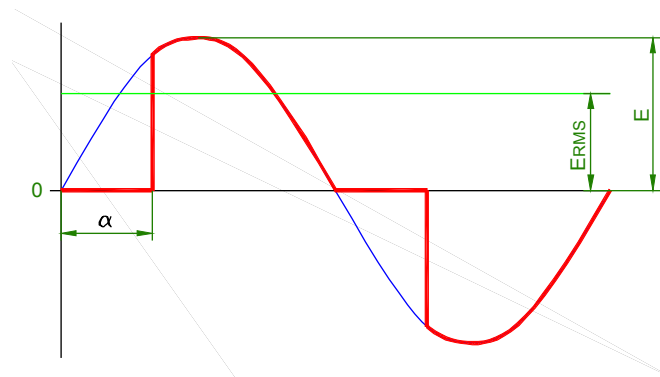
PHASE ANGLE REGULATION.

Phase angle regulation, it's based on the possibility to realize the connection to the mains power supply at any point of the half wave and in a synchronous way. Thus, sinusoidal voltage can be cut in little sectors, so, in this way regulating the load power.

Considering that each sinusoidal half wave corresponds to a conduction of 180° (360° for the full wave), using a delay from 180° to 0° it's possible to regulate the load power from 0 to 100%. This delay value it's called «angle of delay» and it's symbolized with α letter. Also, there's the «conduction angle» which is $180-\alpha$.

E_{RMS} VS ANGLE OF DELAY.

Analyzing the obtained waveform by regulating the angle, we can appreciate that E_{RMS} vs angle of delay is nonlinear, due to the variation of the waveform which ceases to be sinusoidal. It is important to emphasize that in this applications, the measures must be done by a true RMS instrument.



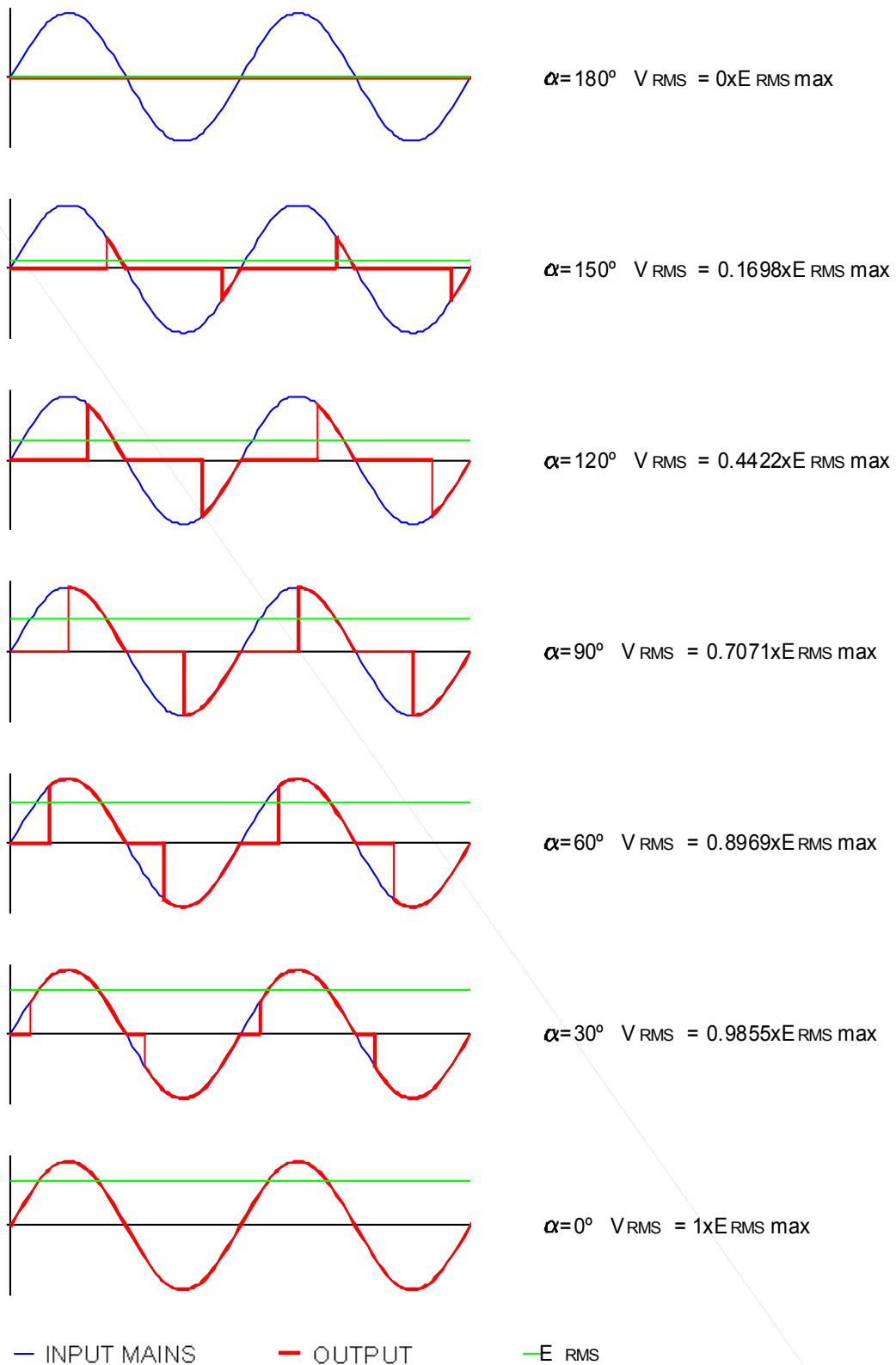
Use the formula below to calculate the E_{RMS} output value versus the angle of delay:

$$E_{RMS}(\alpha) = \frac{E}{\sqrt{2\pi}} \sqrt{\pi - \alpha + \frac{1}{2} \sin 2\alpha}$$

NOTE: α in radians

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Below we can appreciate the waveform and the E_{RMS} values regarding different angle delays.



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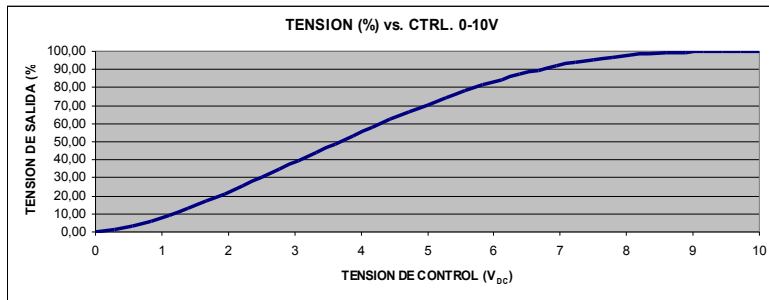
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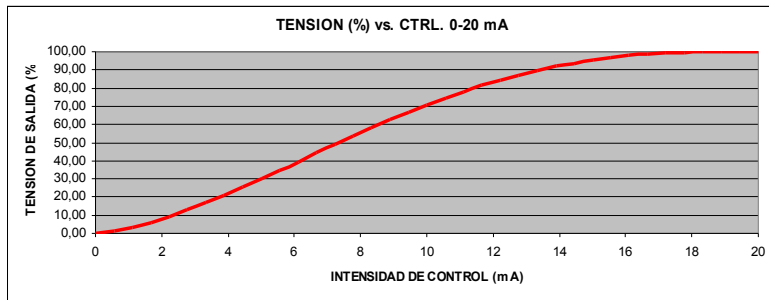
CONTROL SIGNAL VS ANGLE OF DELAY

Common control systems (specially the analogical), uses the control signal to adjust linearly the thyristors angle of conduction, like the relation between the conduction angle (remember that conduction angle is $180-\alpha$) and the E_{RMS} voltage which it's not linear. We will always have a nonlinear relationship between the control signal and the output voltage.

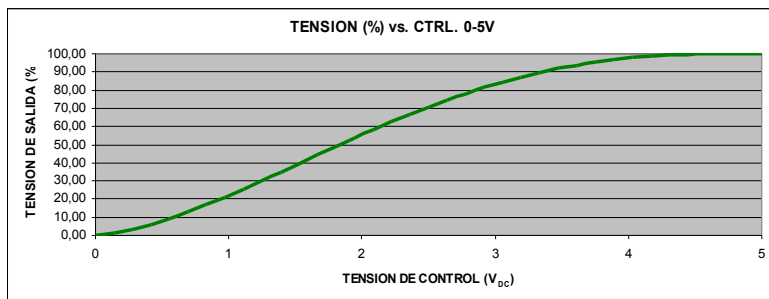
Below the graphics for a common control signals.



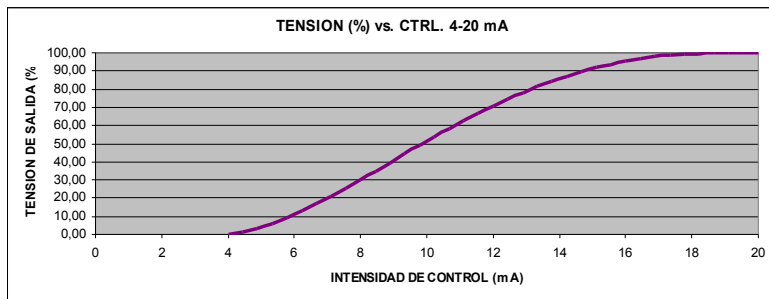
Polynomial approach (valid between 0 and 10)
 $y = 0,0241x^4 - 0,645x^3 + 4,614x^2 + 4,2201x - 0,167$



Polynomial approach (valid between 0 and 20)
 $y = 0,0015x^4 - 0,0806x^3 + 1,1535x^2 + 2,1101x - 0,167$



Polynomial approach (valid between 0 and 5)
 $y = 0,3863x^4 - 5,16x^3 + 18,456x^2 + 8,4403x - 0,167$



Polynomial approach (valid between 0 and 20)
 $y = 0,0037x^4 - 0,2164x^3 + 4,0457x^2 - 20,283x + 29,141$

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